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DANIELA KANE

A Newspaper of British and Foreign Literature Brooks/Cole Publishing Company

Upon publication, the first edition of the CRC Concise Encyclopedia of Mathematics received overwhelming accolades for its unparalleled scope, readability, and utility. It soon took its place among the top selling books in the history of Chapman & Hall/CRC, and its popularity continues unabated. Yet also unabated has been the d

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Catalogue ... Indiana University Press

This edition of Swokowski's text is truly as its name implies: a classic. Groundbreaking in every way when first published, this book is a simple, straightforward, direct calculus text. It's popularity is directly due to its broad use of applications, the easy-to-understand writing style, and the wealth of examples and exercises which reinforce conceptualization of the subject matter. The author wrote this text with three objectives in mind. The first was to make the book more student-oriented by expanding discussions and providing more examples and figures to help clarify concepts. To further aid students, guidelines for solving problems were added in many sections of the text. The second objective was to stress the usefulness of calculus by means of modern applications of derivatives and integrals. The third objective, to make the text as accurate and error-free as possible, was accomplished by a careful examination of the exposition, combined with a thorough checking of each example and exercise.

An Illustrated Monthly Record of the Book, Stationery, Leather Goods, and Allied Trades CRC Press

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Probability and Conditional Expectations bridges the gap between books on probability theory and statistics by providing the probabilistic concepts estimated and tested in analysis of variance, regression analysis, factor analysis, structural equation modeling, hierarchical linear models and analysis of qualitative data. The authors emphasize the theory of conditional expectations that is also fundamental to conditional independence and conditional distributions. Probability and Conditional Expectations Presents a rigorous and detailed mathematical treatment of probability

theory focusing on concepts that are fundamental to understand what we are estimating in applied statistics. Explores the basics of random variables along with extensive coverage of measurable functions and integration. Extensively treats conditional expectations also with respect to a conditional probability measure and the concept of conditional effect functions, which are crucial in the analysis of causal effects. Is illustrated throughout with simple examples, numerous exercises and detailed solutions. Provides website links to further resources including videos of courses delivered by the authors as well as R code exercises to help illustrate the theory presented throughout the book.

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This book treats the derivation and implementation of a unified particle finite element formulation for the solution of fluid and solid mechanics, Fluid-Structure Interaction (FSI) and coupled thermal problems. FSI problems are involved in many engineering branches, from aeronautics to civil and biomedical engineering. The numerical method proposed in this book has been designed to deal with a large part of these. In particular, it is capable of simulating accurately free-surface fluids interacting with structures that may undergo large displacements, suffer from thermo-plastic deformations and even melt. The method accuracy has been successfully verified in several numerical examples. The thesis also contains the application of the proposed numerical strategy for the simulation of a real industrial problem. This thesis, defended at the Universitat Politecnica de Catalunya in 2015, was selected (ex aequo) as the best PhD thesis in numerical methods in Spain for the year 2015 by the Spanish Society of Numerical Methods in Engineering (SEMNI).

Library Bulletin CRC Press

This book illustrates basic principles, along with the development of the advanced algorithms, to realize smart robotic systems. It speaks to strategies by which a robot (manipulators, mobile robot, quadrotor) can learn its own kinematics and dynamics from data. In this context, two major issues have been dealt with; namely, stability of the systems and experimental validations. Learning algorithms and techniques as covered in this book easily extend to other robotic systems as well. The book contains MATLAB- based examples and c-codes under robot operating systems (ROS) for experimental validation so that readers can replicate these algorithms in robotics platforms.

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